

# ***Synchronizing Automata Preserving a Chain of Partial Orders***

M. V. Volkov

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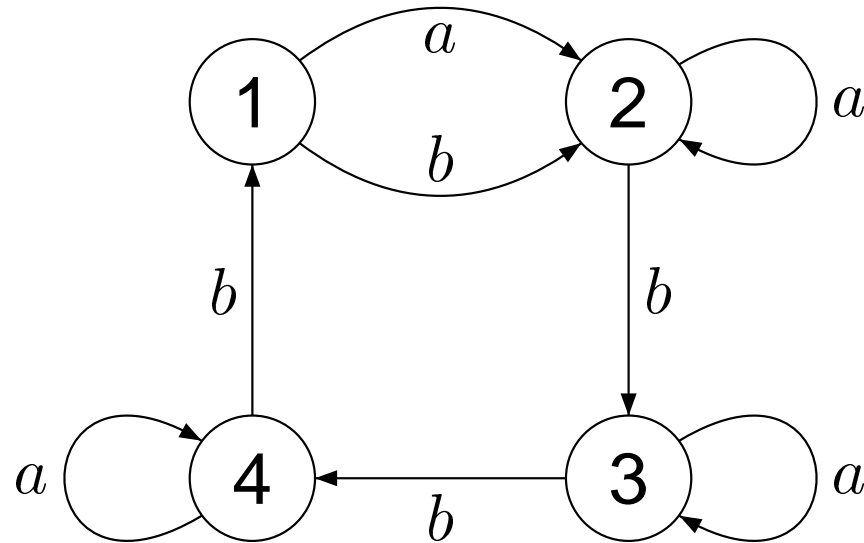
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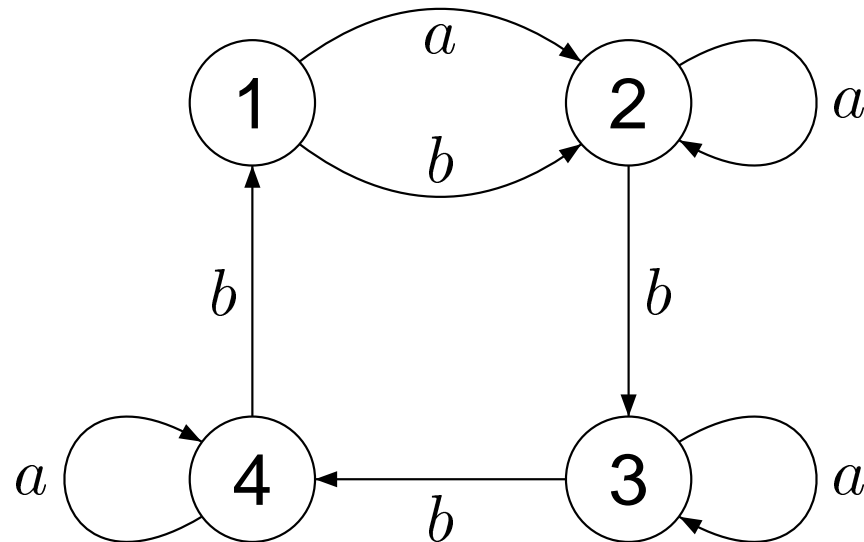
$|Q \cdot w| = 1$ . Here  $Q \cdot v$  stands for  $\{\delta(q, v) \mid q \in Q\}$ .

Any word  $w$  with this property is said to be a *reset word* for the automaton.

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A reset sequence of actions is  $abbbabbba$ . Applying it at any state brings the automaton to the state 2.

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Think of a satellite which loops around the Moon and cannot be controlled from the Earth while “behind” the Moon (Černý’s original motivation).

# *Engineering Applications*

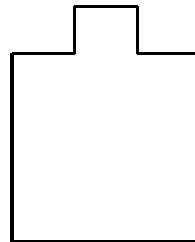
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In the 80s, the notion was reinvented by engineers working in *robotics* or, more precisely, *robotic manipulation* which deals with part handling problems in industrial automation such as part feeding, fixturing, loading, assembly and packing (and which is therefore of utmost and direct practical importance).

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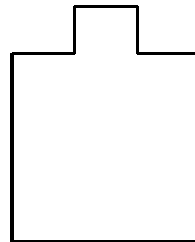
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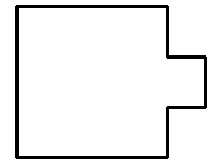
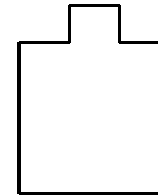
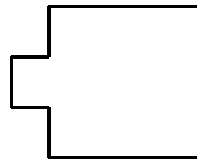
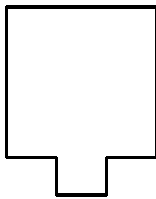


Such parts arrive at manufacturing sites in boxes and they need to be sorted and oriented before assembly.

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Assume that only four initial orientations of the part shown above are possible, namely, the following ones:



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Suppose that prior the assembly the part should take the “bump-left” orientation (the second one on the picture). Thus, one has to construct an orienter which action will put the part in the prescribed position independently of its initial orientation.

# ***Engineering Applications***

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We put parts to be oriented on a conveyer belt which takes them to the assembly point and let the stream of the details encounter a series of passive obstacles of two types (*high* and *low*) placed along the belt.

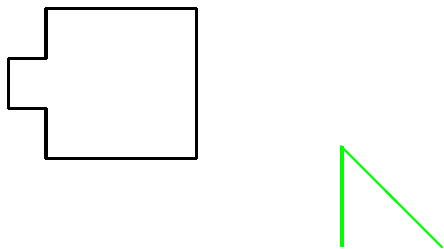


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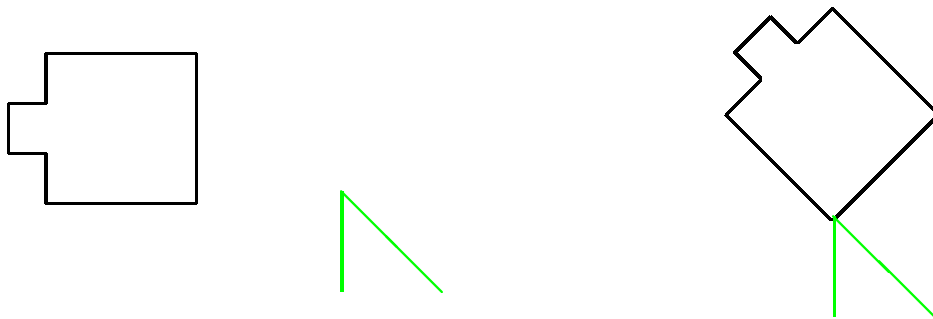
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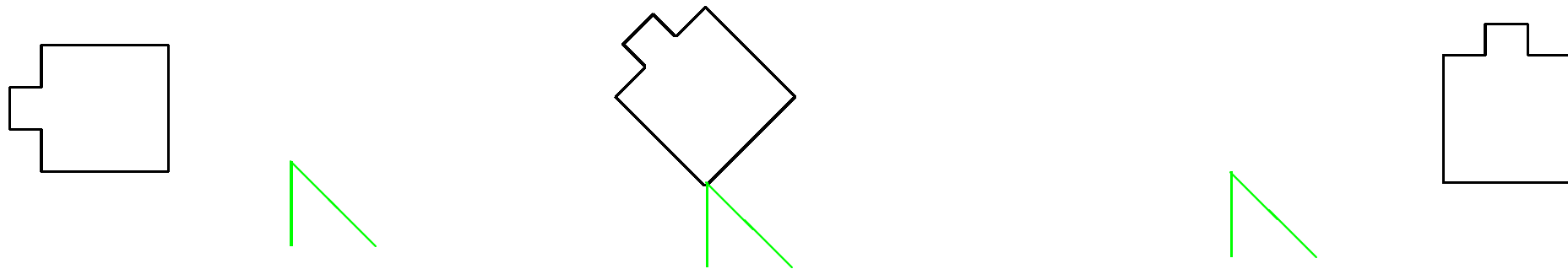


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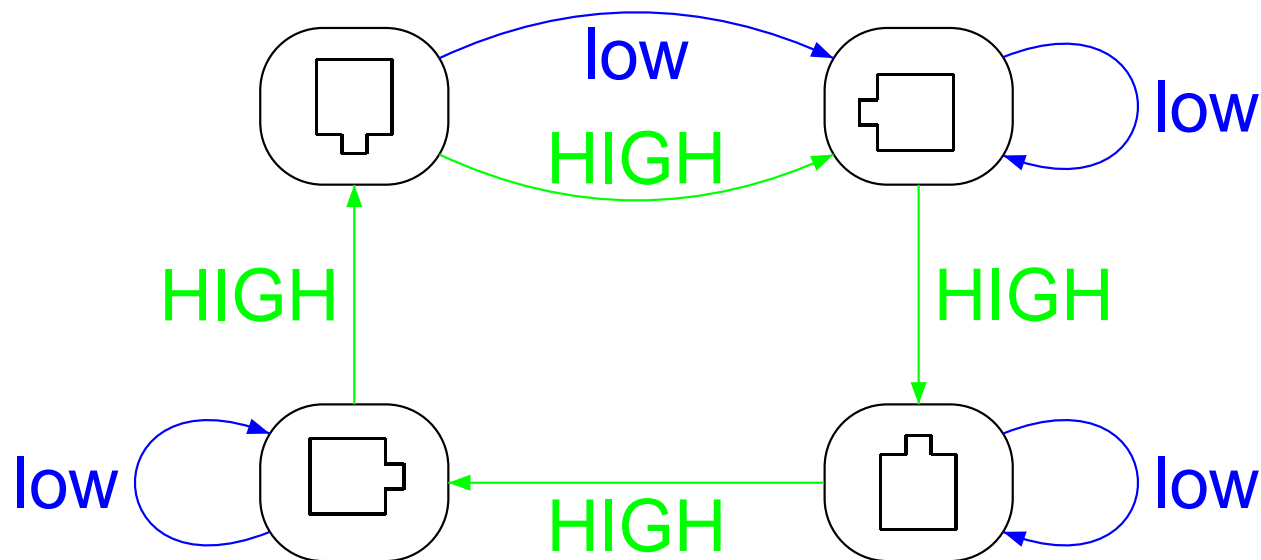
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The following schema summarizes how the obstacles effect the orientation of the part in question:

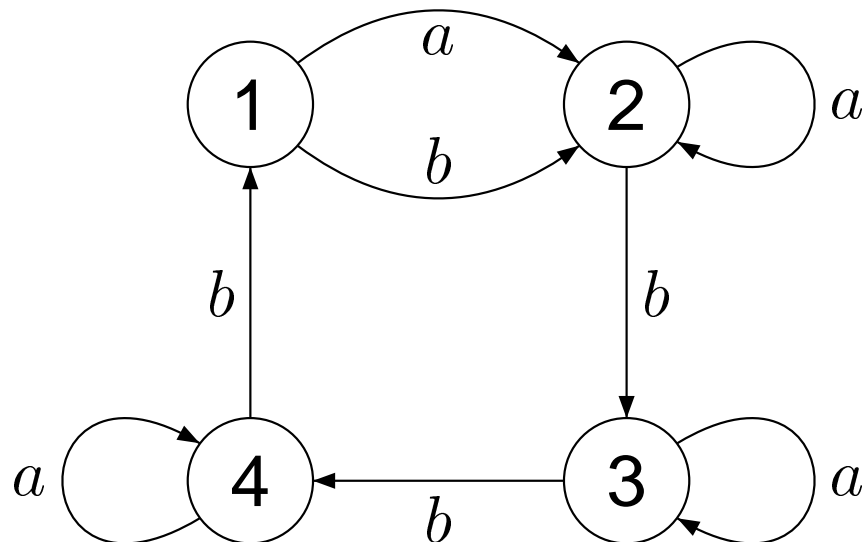


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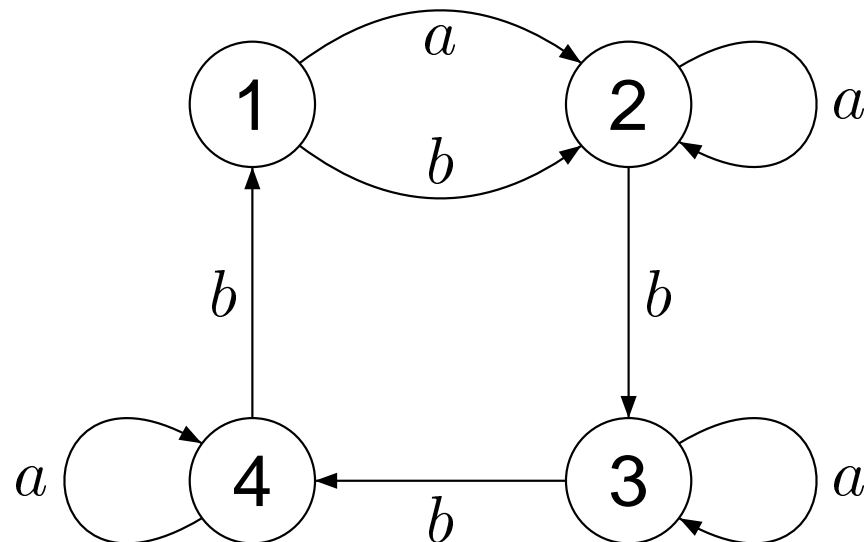
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low-HIGH-HIGH-HIGH-low-HIGH-HIGH-HIGH-low yields the desired sensorless orienter.



## *Further Applications*

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In *DNA-computing*, there is a fast progressing work by Ehud Shapiro's group on "*soup of automata*" (Programmable and autonomous computing machine made of biomolecules, Nature 414, no.1 (November 22, 2001) 430–434; DNA molecule provides a computing machine with both data and fuel, Proc. National Acad. Sci. USA 100 (2003) 2191–2196, etc).

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The simply looking conjecture is still open in general!!

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Synchronization issues remain difficult when restricted to  $A_p$ .

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The gap between the upper and the lower bounds is rather drastic.



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An idea: consider certain properties that guarantee aperiodicity and are easier to check.

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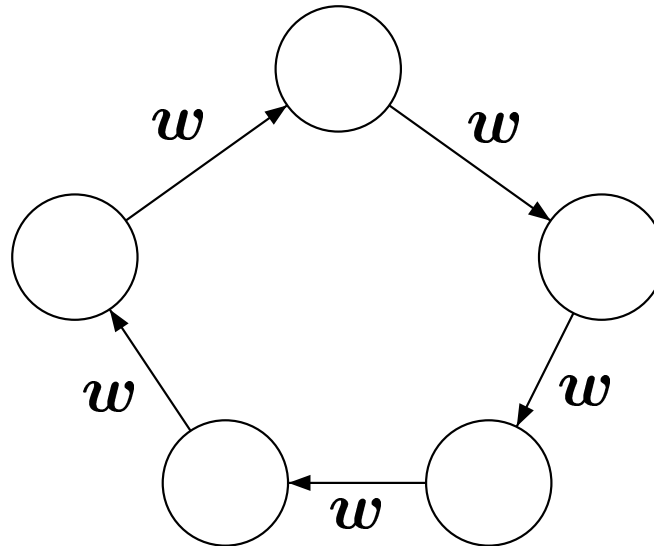


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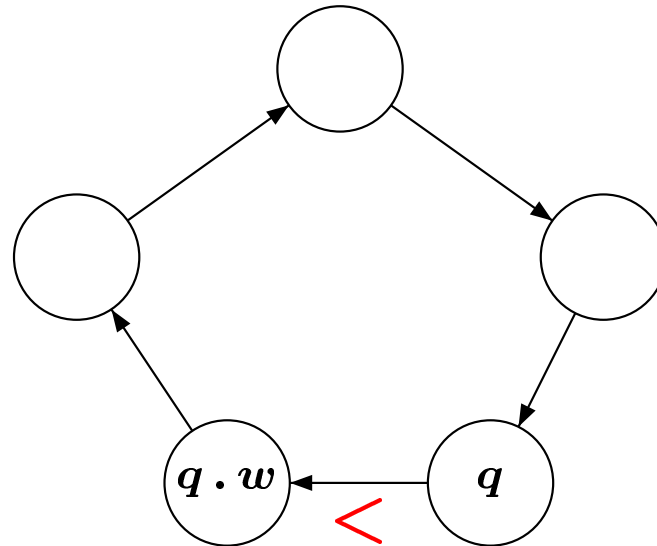


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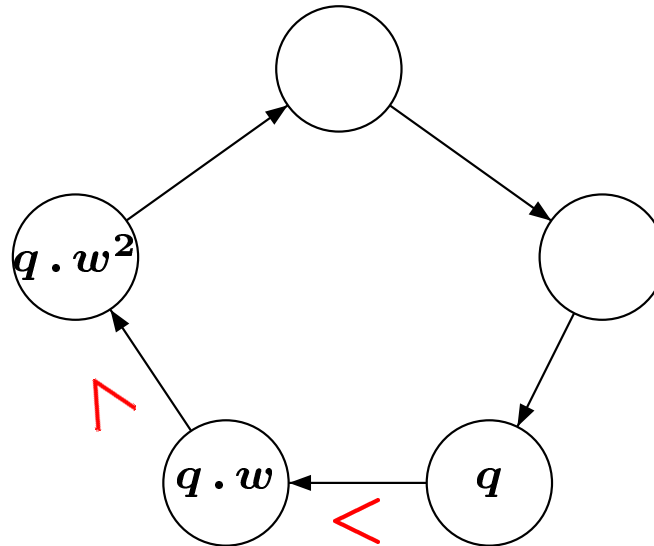


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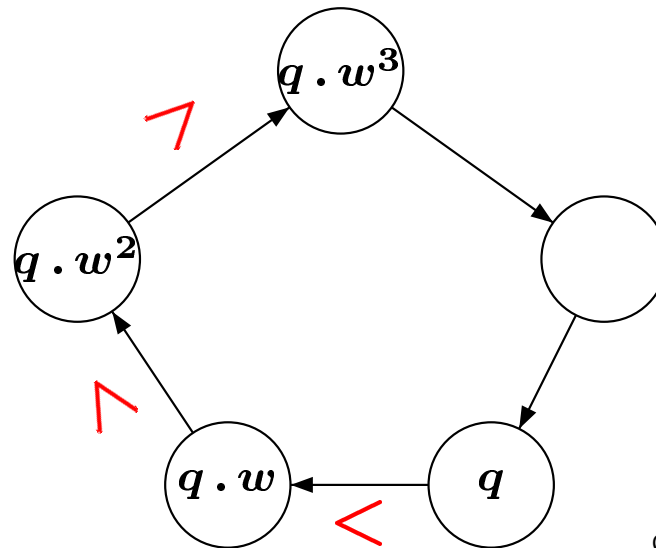


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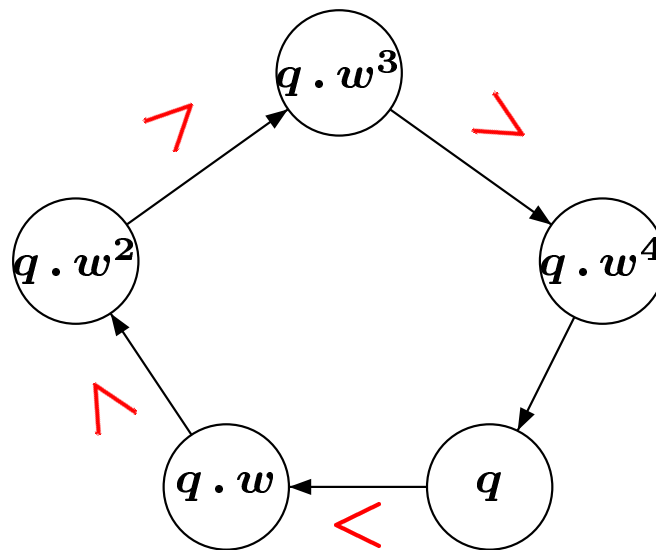


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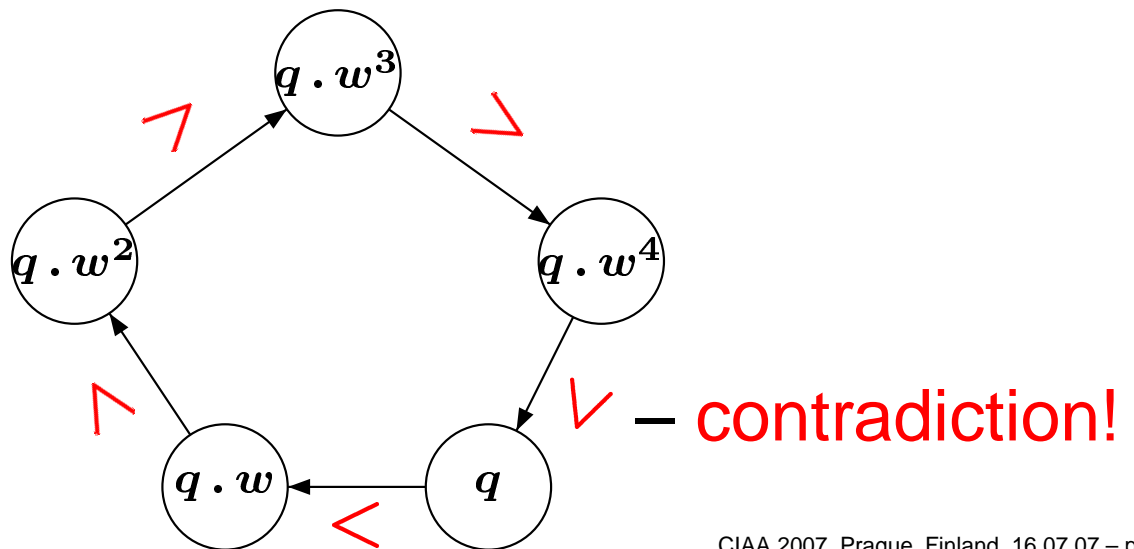


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A DFA  $\mathcal{A} = \langle Q, \Sigma, \delta \rangle$  is *monotonic* if  $Q$  admits a linear order  $\leq$  such that, for  $a \in \Sigma$ , the transformation  $\delta(\_, a)$  of  $Q$  preserves  $\leq$ :

$$p \leq q \Rightarrow \delta(p, a) \leq \delta(q, a).$$

Monotonic automata are aperiodic (known and easy).



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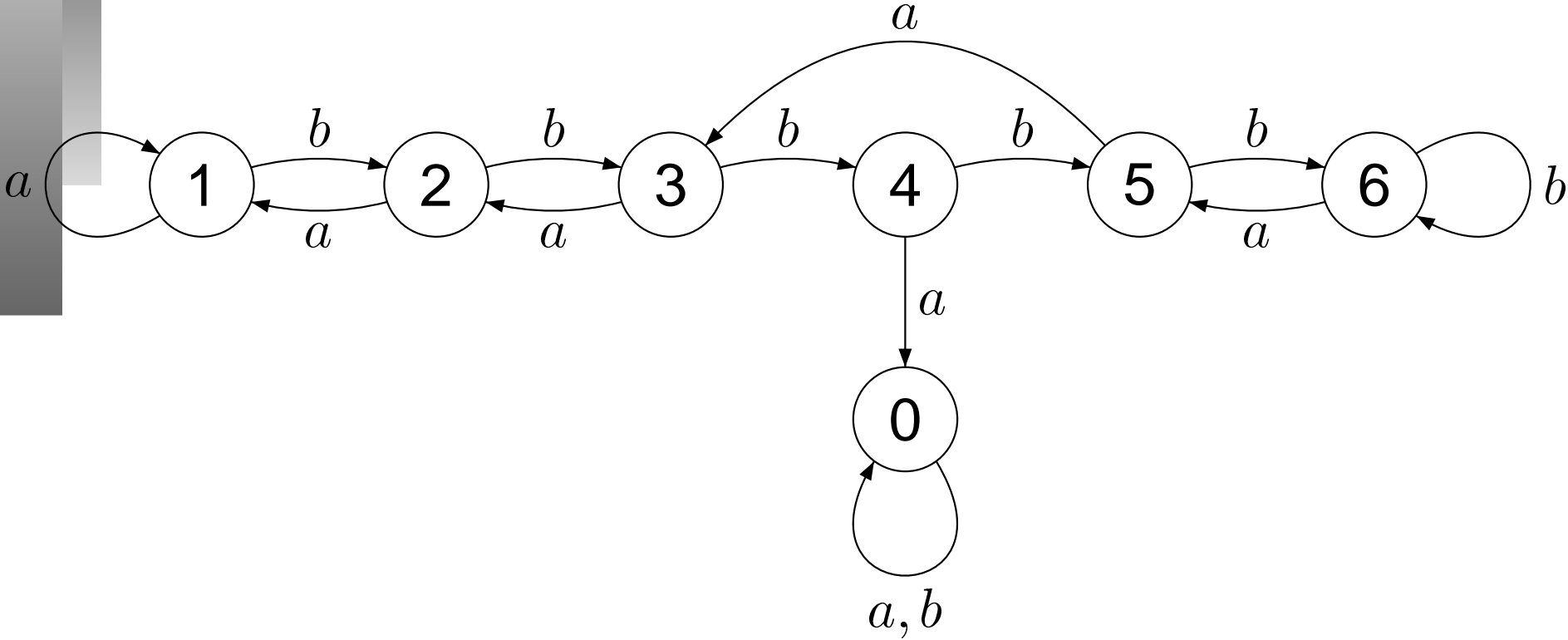
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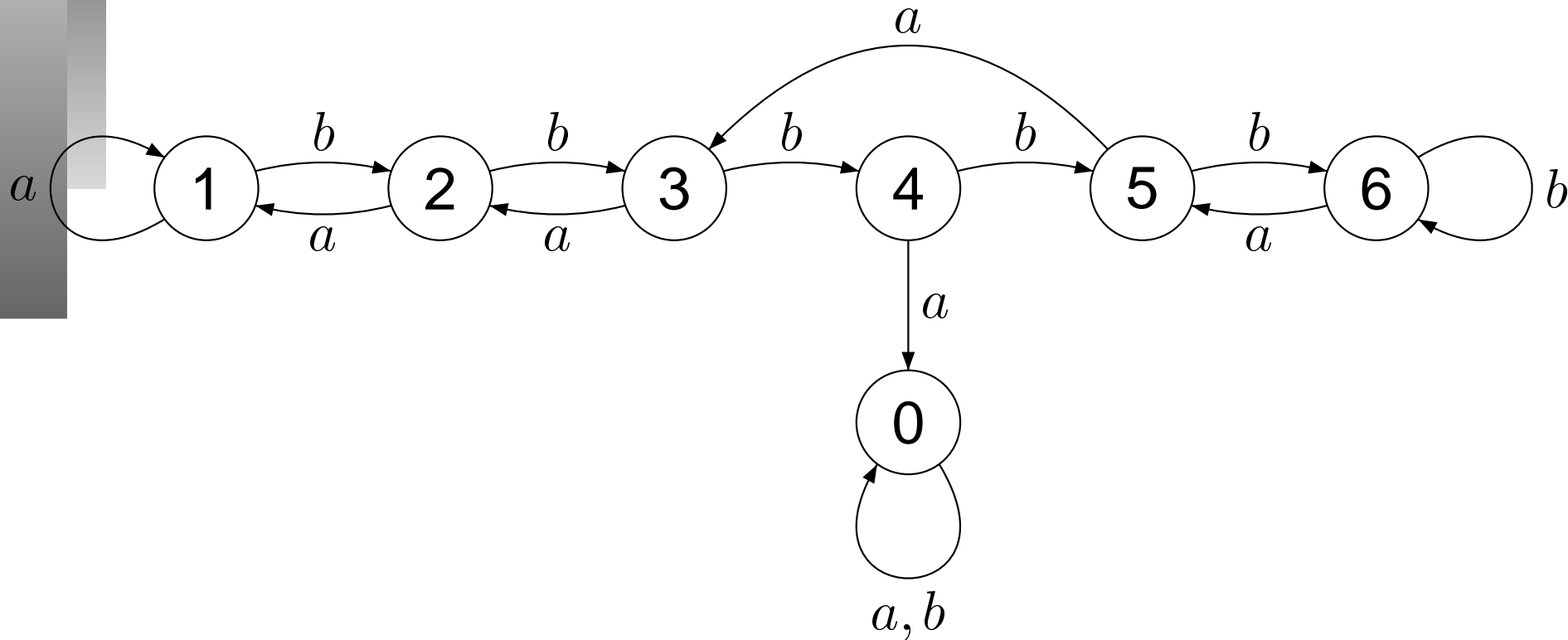
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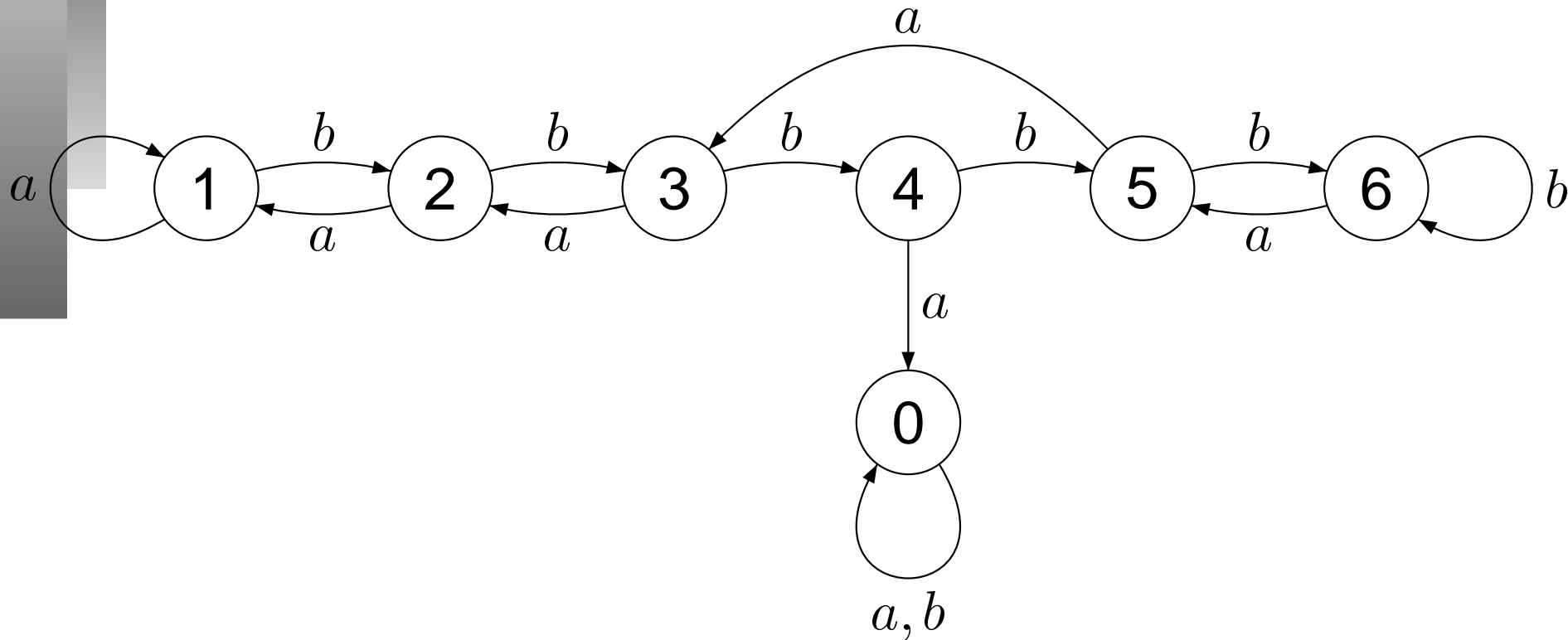


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# Generalized Monotonicity

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A binary relation  $\rho$  on the state set  $Q$  of a DFA  $\mathcal{A} = \langle Q, \Sigma, \delta \rangle$  is a *stable* if  $(p, q) \in \rho$  implies  $(\delta(p, a), \delta(q, a)) \in \rho$  for all  $p, q \in Q$  and  $a \in \Sigma$ .

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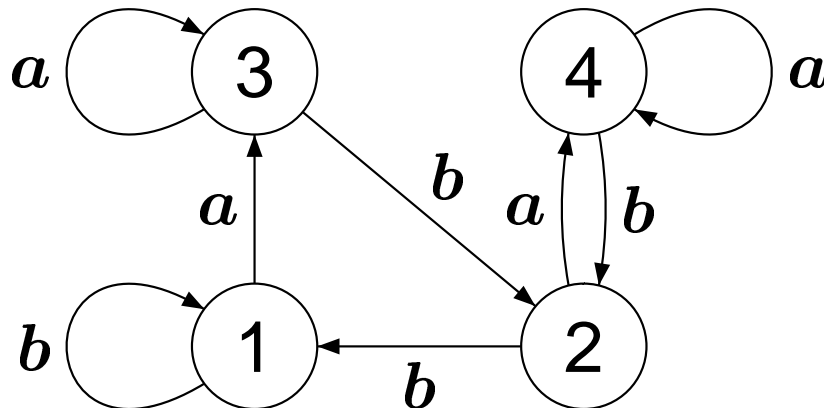
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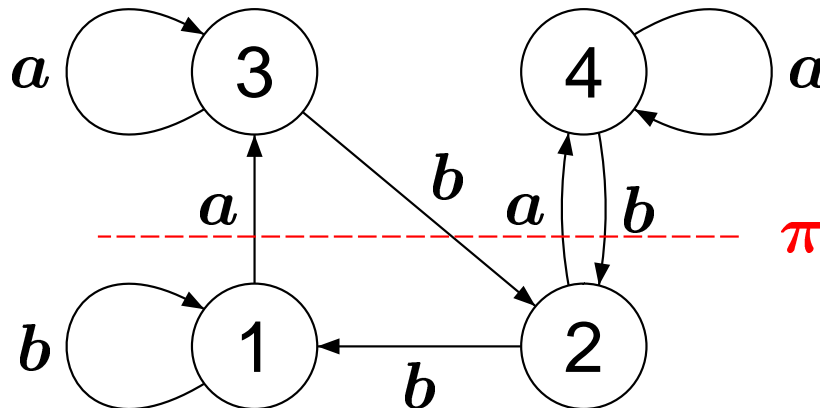
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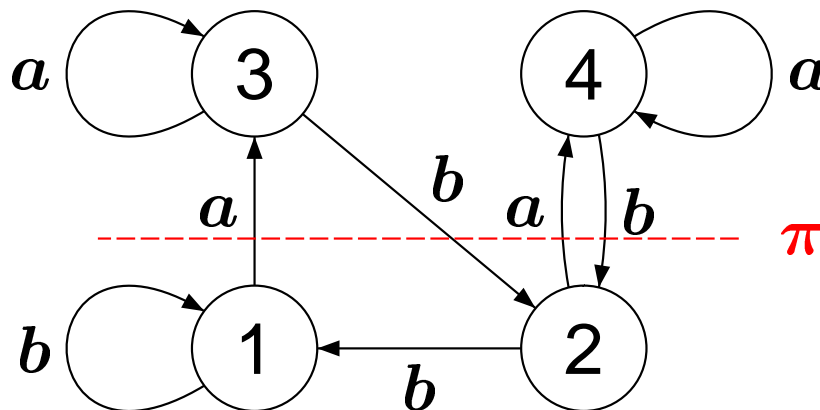
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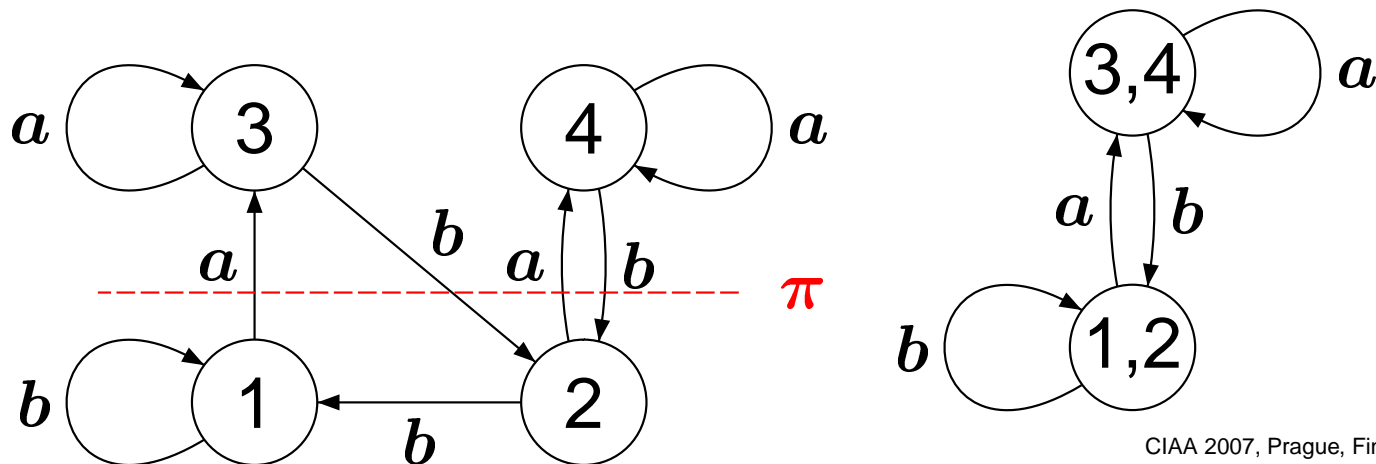
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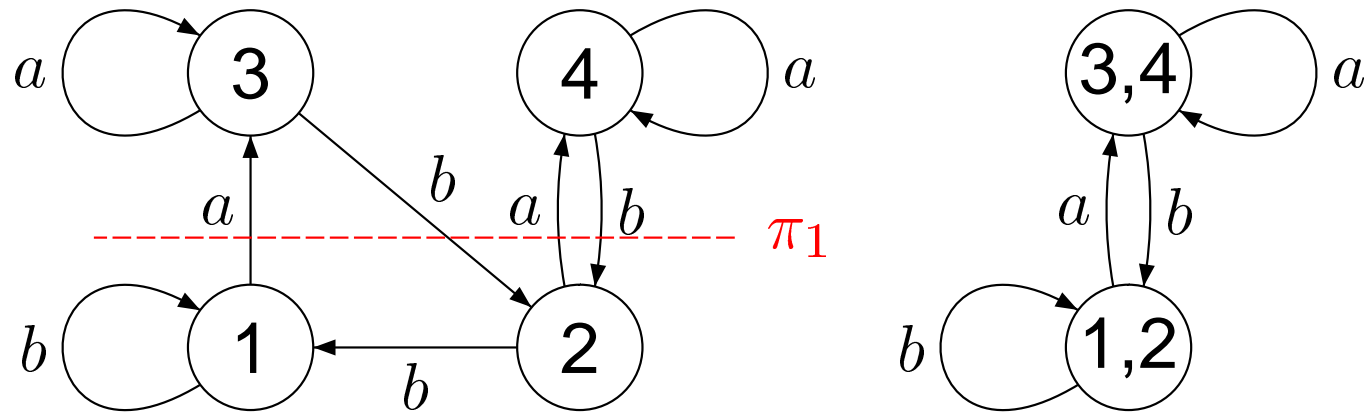
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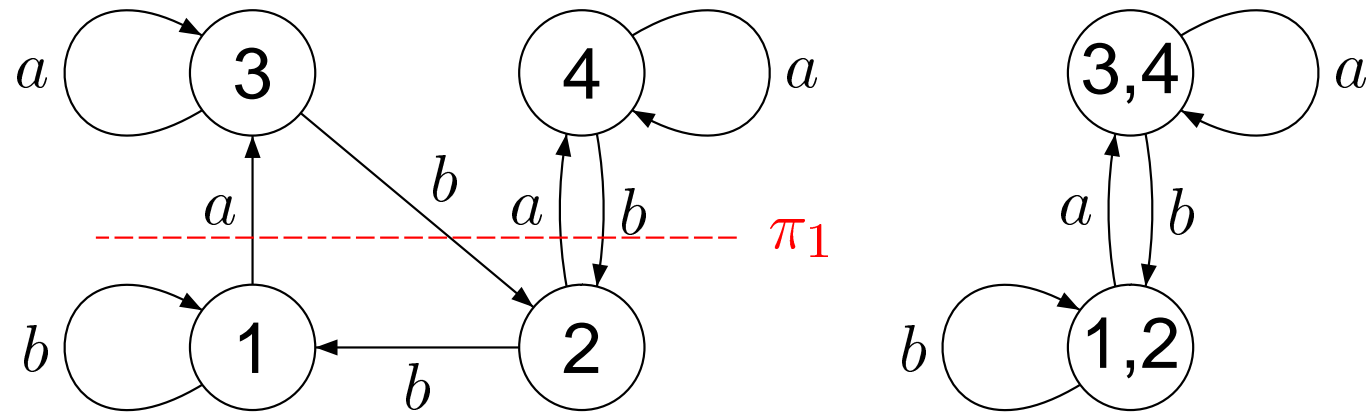
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The automaton in the previous example is a generalized monotonic automaton of level 2.

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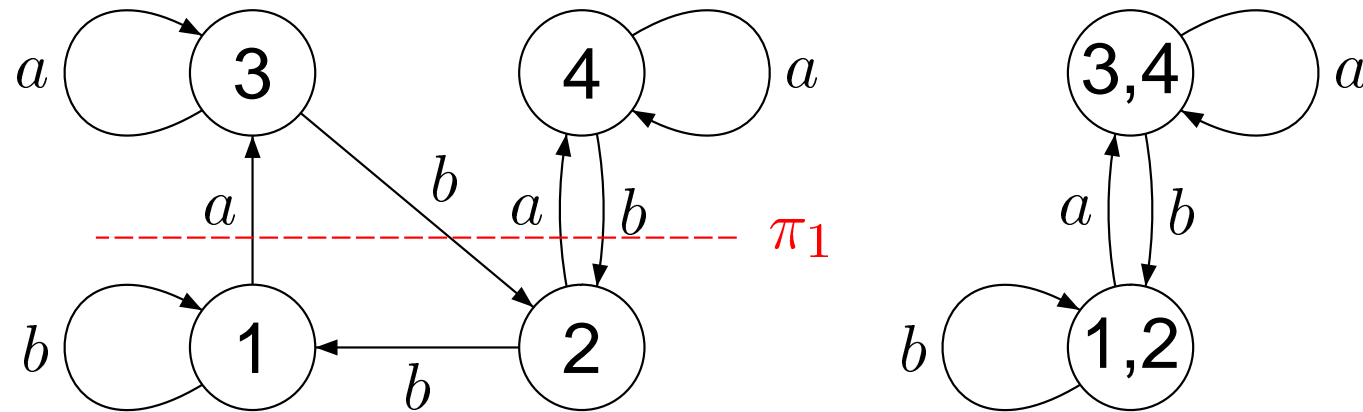


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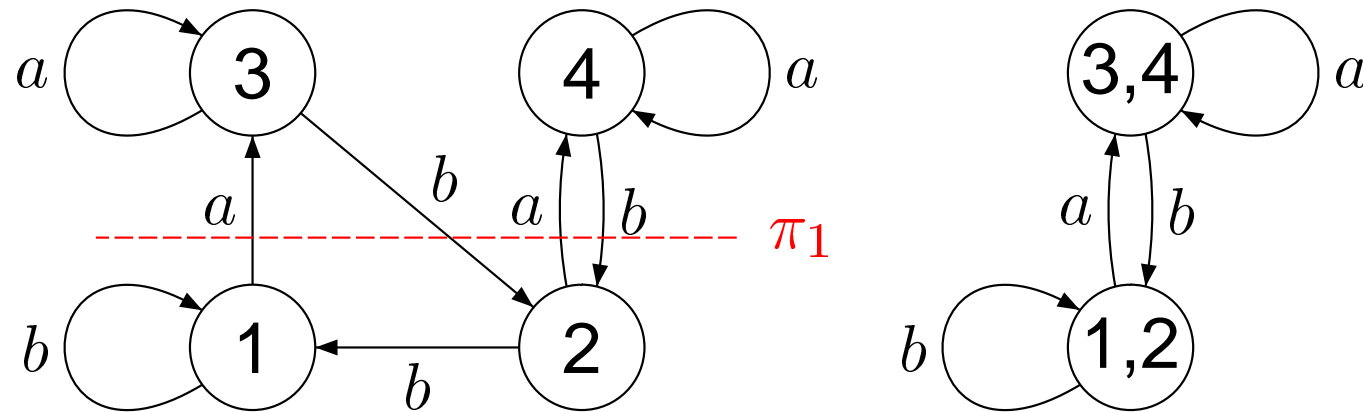
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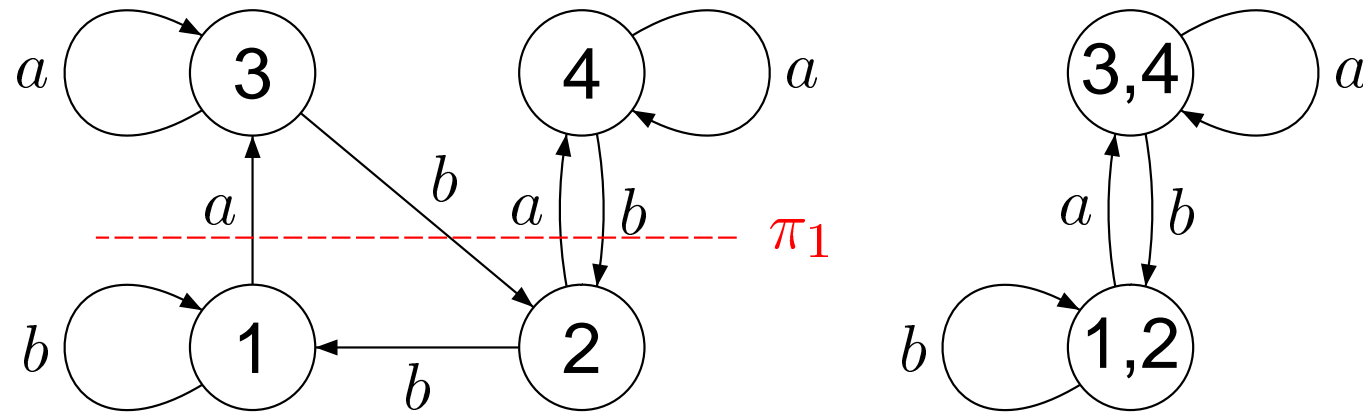
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It can be shown that the automaton is not monotonic. Moreover, it cannot be emulated by any monotonic automaton.

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However, generalized monotonic automata are **not** representative for the class  $A_p$  from the synchronization point of view: Ananichev and  $\sim$  (2005) proved that every generalized monotonic synchronizing automaton with  $n$  states has a reset word of length  $\leq n - 1$ .

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Thus, we just dropped the restriction that the order  $\rho_i / \pi_{i-1}$  is linear on each  $\pi_i / \pi_{i-1}$ -class.

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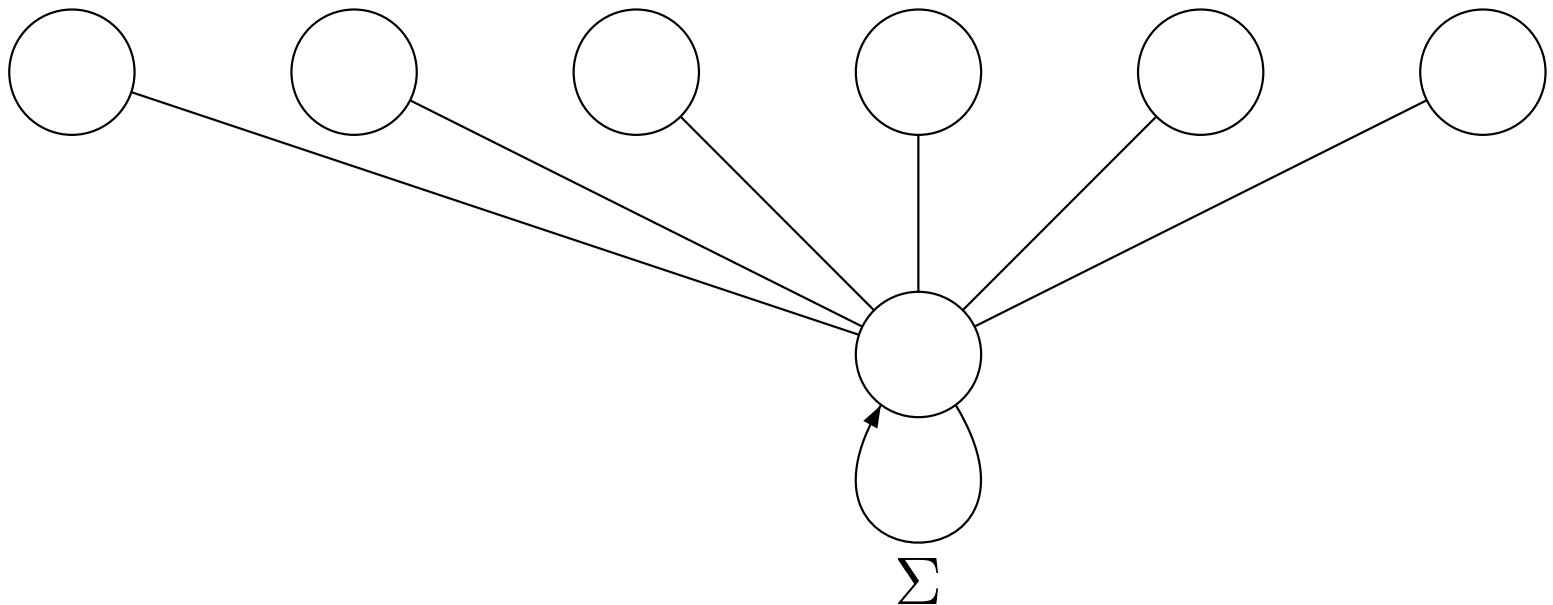
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